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# Data Structures for Computational Geometry

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21<sup>st</sup> June, 2007

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<http://www.cs.tufts.edu/research/geometry/>

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# Data Structures

Preprocess data to support:

1. Fast queries
2. Fast updates
3. Using little space

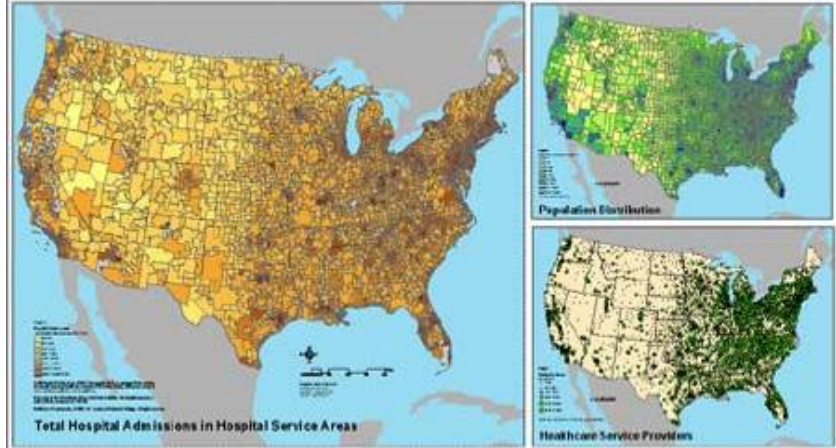
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# Data Structures

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- There are two different approaches to answer a query.
  - Algorithmic (one-shot) approach:
    - Solve the problem from scratch for every query.
  - Data structural approach:
    - Spend some time preprocessing the data.
    - Answer queries quickly.
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# Data Structures

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- Algorithmic solution is **efficient** if we have to answer only once.
  - But if we are going to query many times data structural approach is preferable.
  - We measure efficiency in term of **computational complexity**.
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# Dynamic Data Structures

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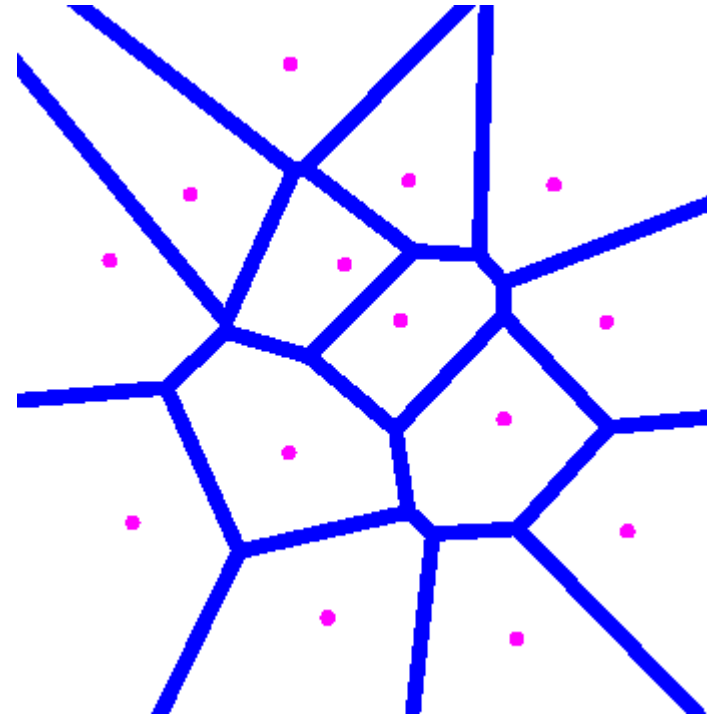
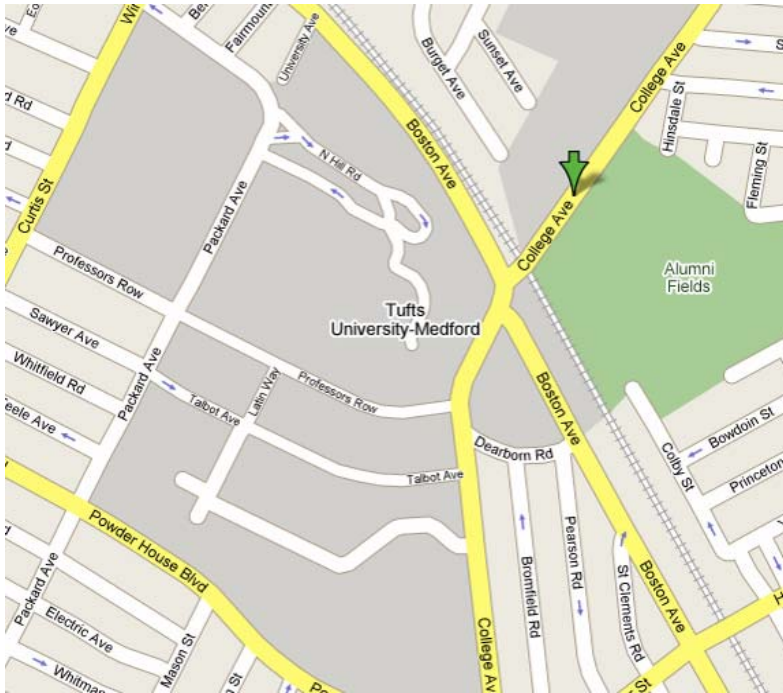
- Sometime we need to **insert** new data or **delete** some old data. Insertions and deletions are known as **updates**.
  - A data structure that supports updates is called **dynamic**.
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# Five Problems in Geometry

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## Post Office Problem (Voronoi Diagrams)



Where is the closest post office (pizza place)?

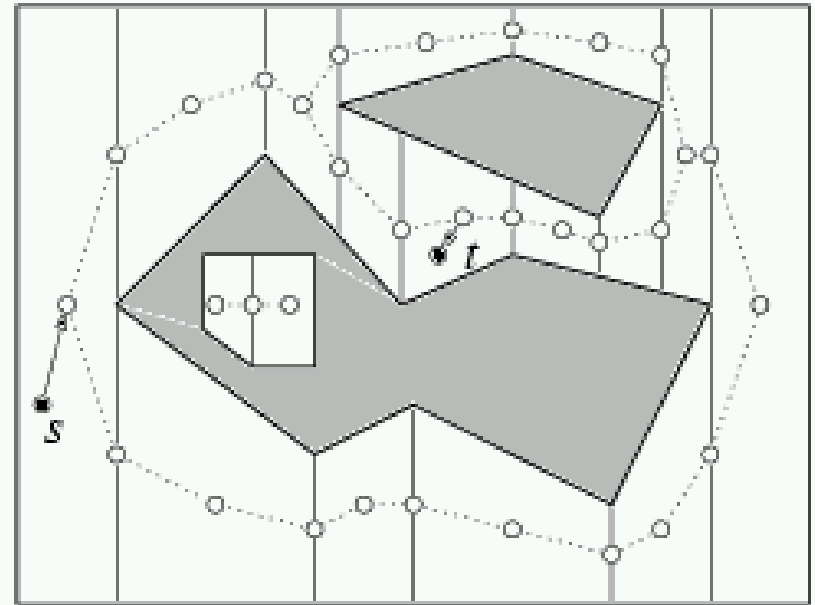
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# Five Problems in Geometry

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## Robot Motion Planning (Trapezoidal Maps)



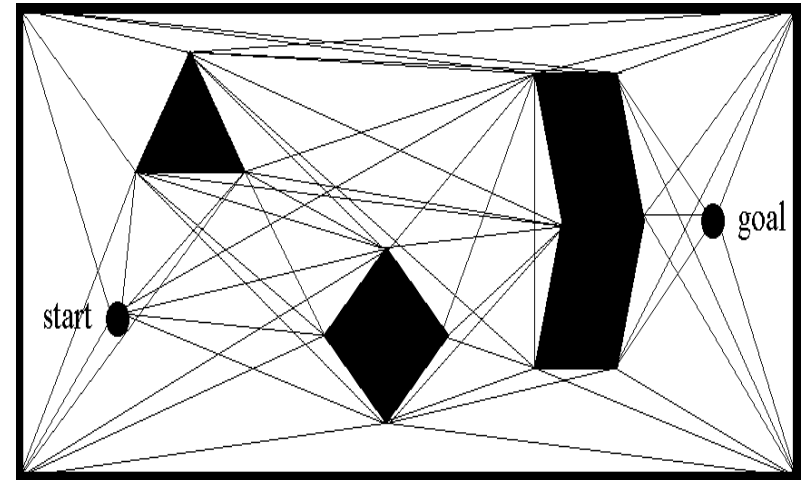
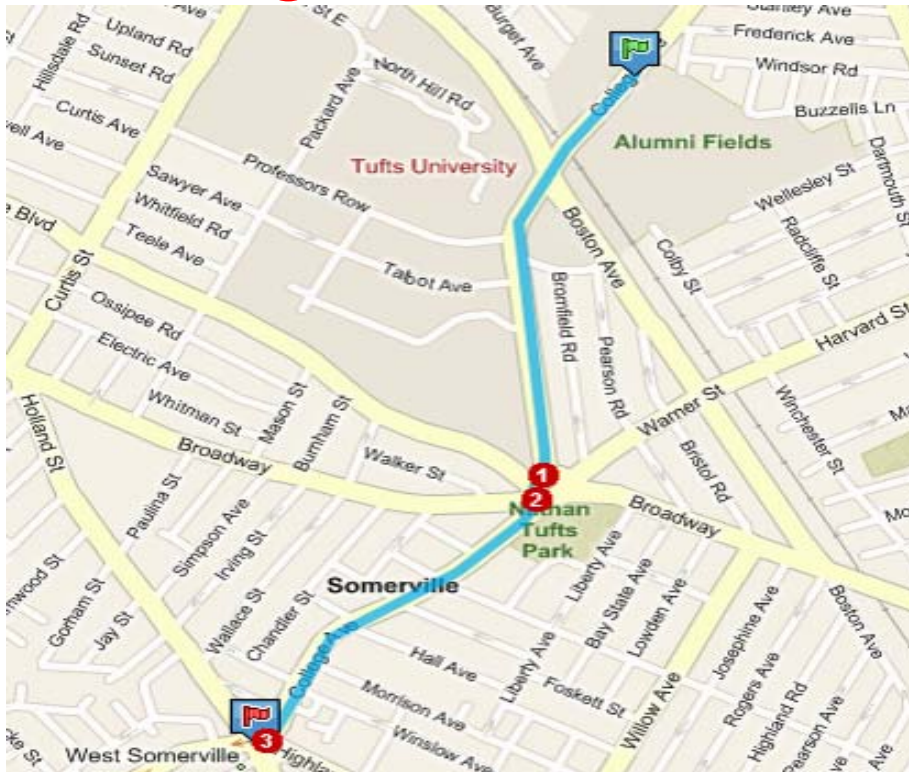
Find an obstacle-avoiding path from source to destination.

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# Five Problems in Geometry

## Finding the Shortest Route (Visibility Graphs)



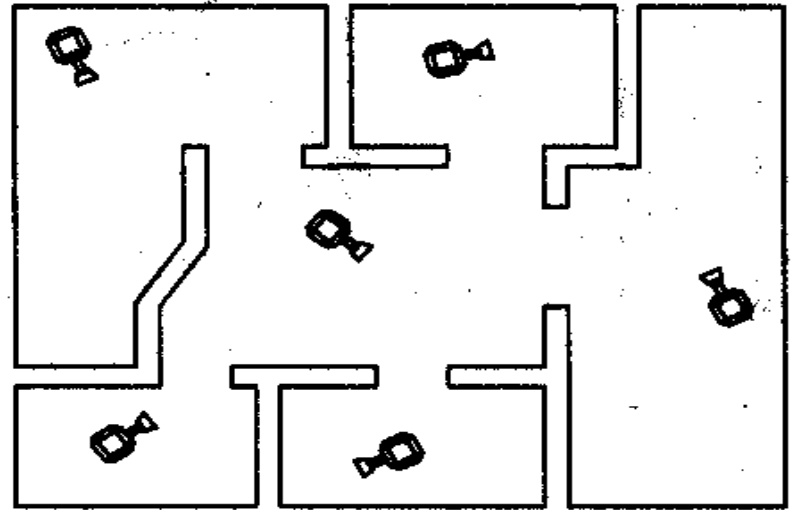
Find the shortest (distance/time) path from Halligan to Davis Square.



# Five Problems in Geometry

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## Guarding an Art Gallery (Triangulation)

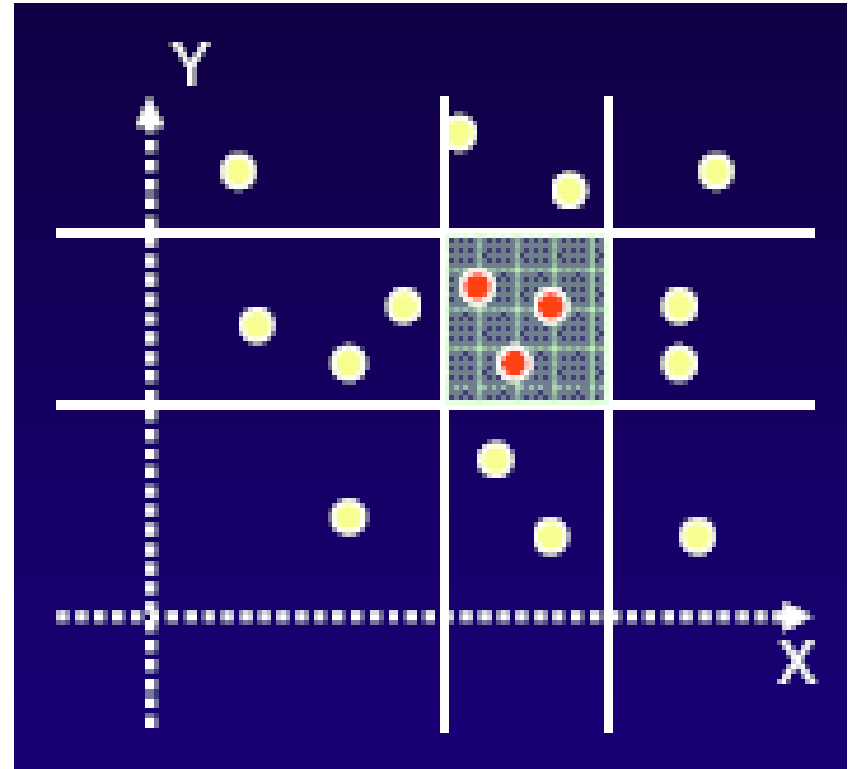
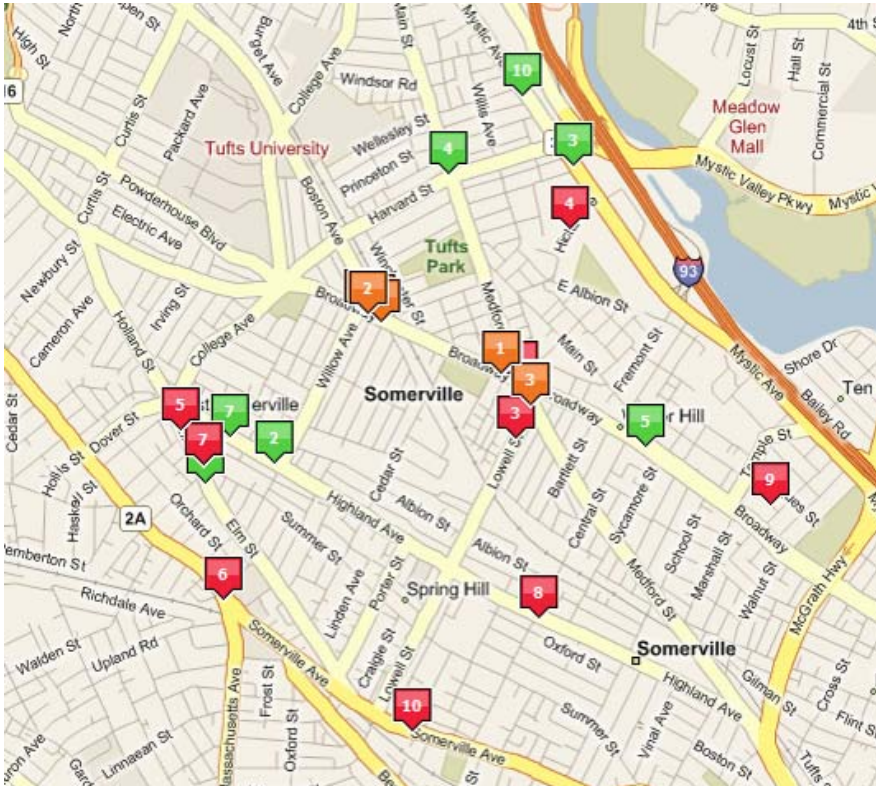


1. How many cameras do we need to guard a given gallery?
  2. Where should we place these cameras?
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# Five Problems in Geometry

## Querying a Database (Range Searching)



How many restaurants are there around Tufts University?

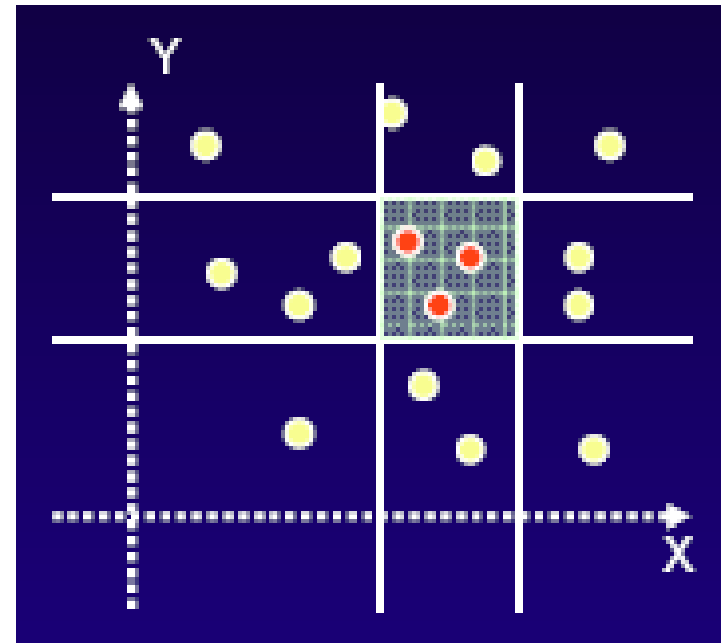


# Range Searching in Detail

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## Orthogonal Range Searching

Given a set of  $n$  points in the plane, preprocess them such that **reporting or counting the points inside query (axis-parallel) rectangle** would be most efficient.



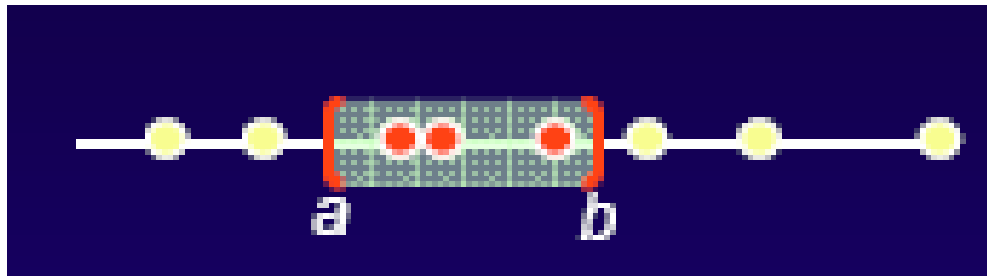


# Range Searching in Detail

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## Range Searching—1D

1. Points are real numbers
2. Query is just an interval  $[a,b]$



What is the simplest (naïve) solution?

Just look at each point, and count those points which lie within the interval.

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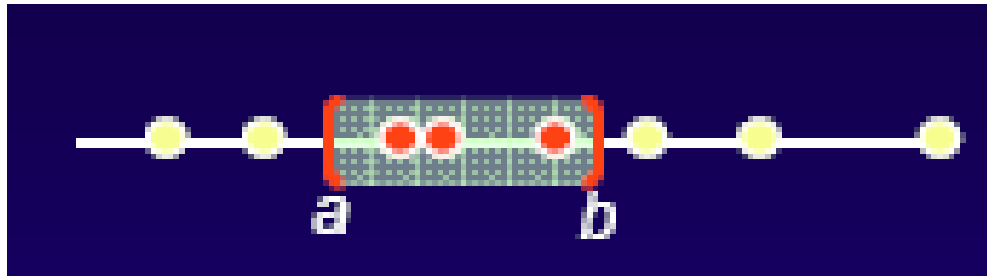


# Range Searching in Detail

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## Range Searching—1D

1. Points are real numbers
2. Query is just an interval  $[a,b]$



What is a more **efficient** solution?

Sort the points (preprocessing), and then for each query just use binary search.

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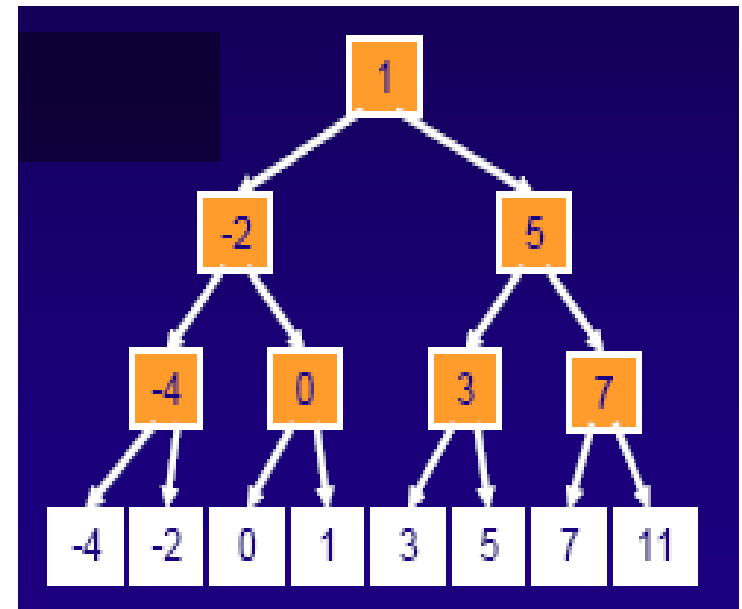


# Balanced Binary Search Trees

## Range Searching—1D

We can store the sorted points in an array. But arrays do not support efficient insertion/deletions.

So we need **balanced binary search trees** for dynamic range searching.

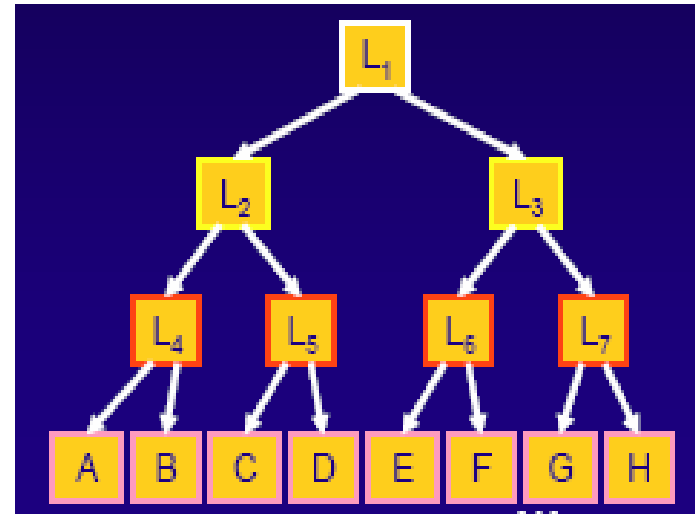
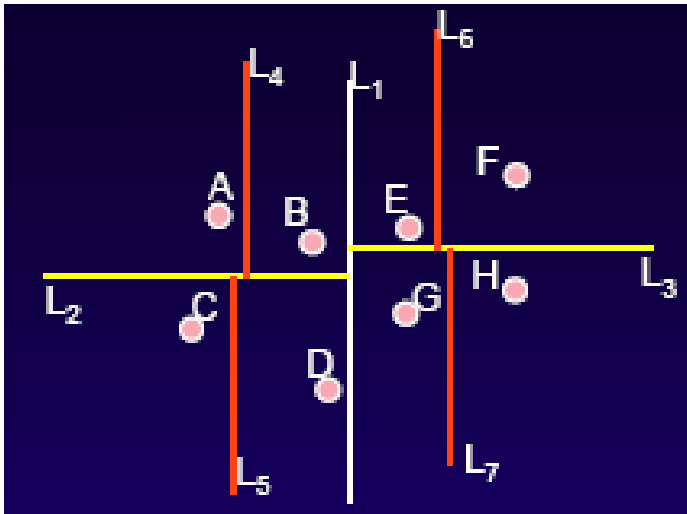




# Range Searching in Detail

## Range Searching—2D

1. Given  $n$  points in the plane
2. Query is an axis-parallel rectangle



Solution = kd Trees



# Thanks for Listening!

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## Related Courses

1. Data Structures (Comp 15)
  2. Algorithms (Comp 160)
  3. Computational Geometry (Comp 163)
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