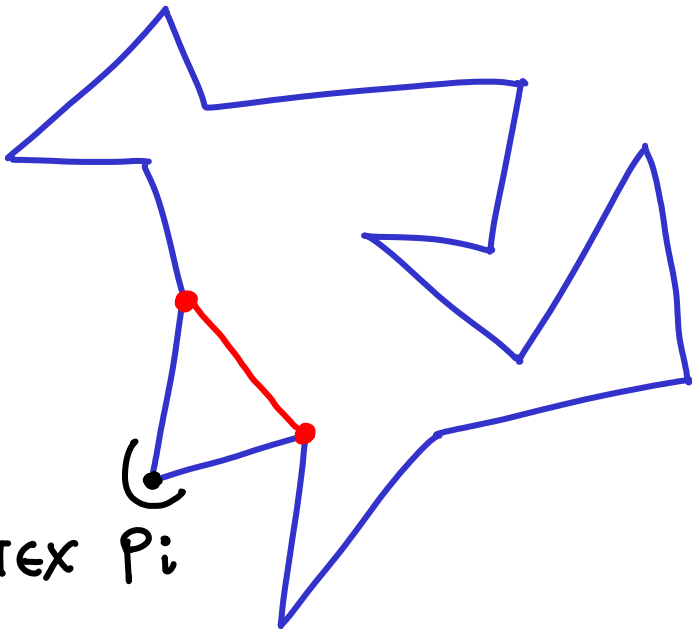


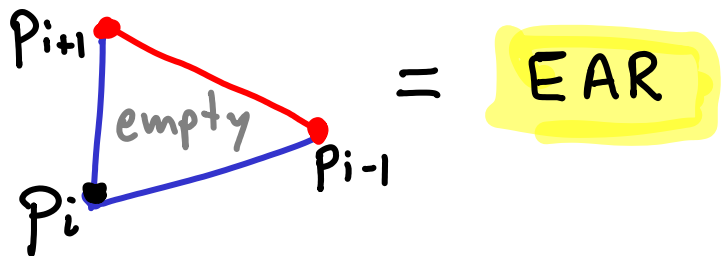
•—• diagonal / chord

- vertex to vertex
- inside polygon
- splits polygon in 2

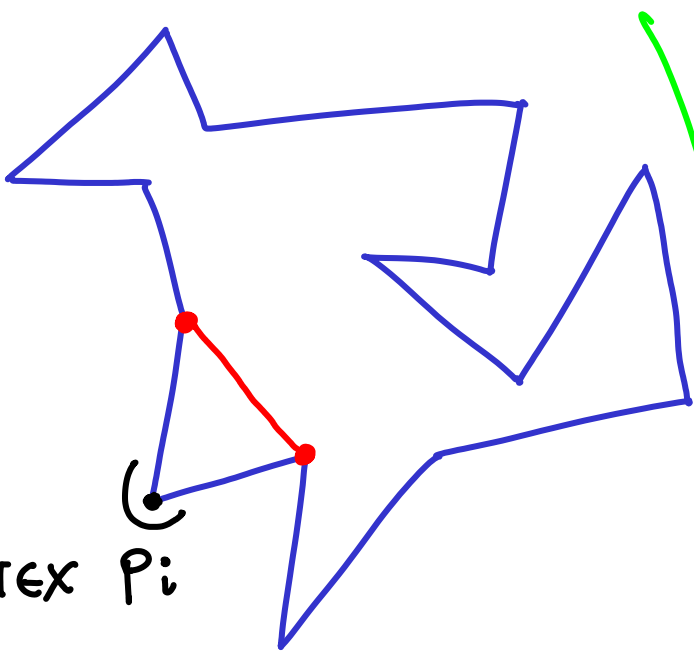
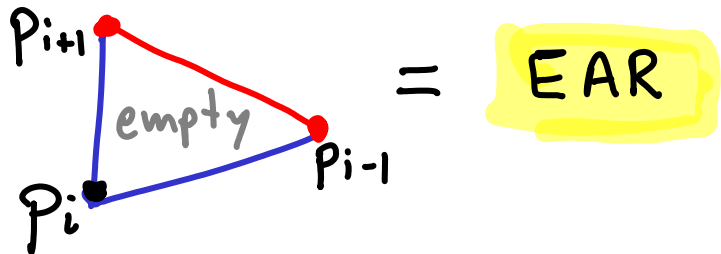
How WOULD YOU FIND A DIAGONAL ?



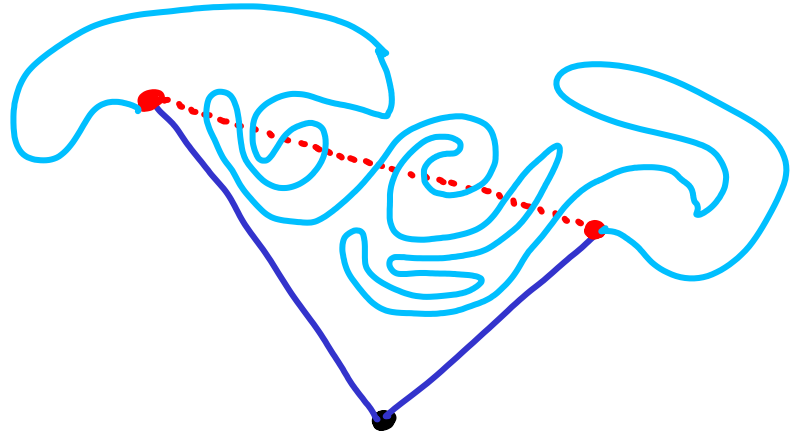
- PICK A CONVEX VERTEX P_i
- TRY $P_{i-1} P_{i+1}$
- IF NOT INTERSECTED, DONE.



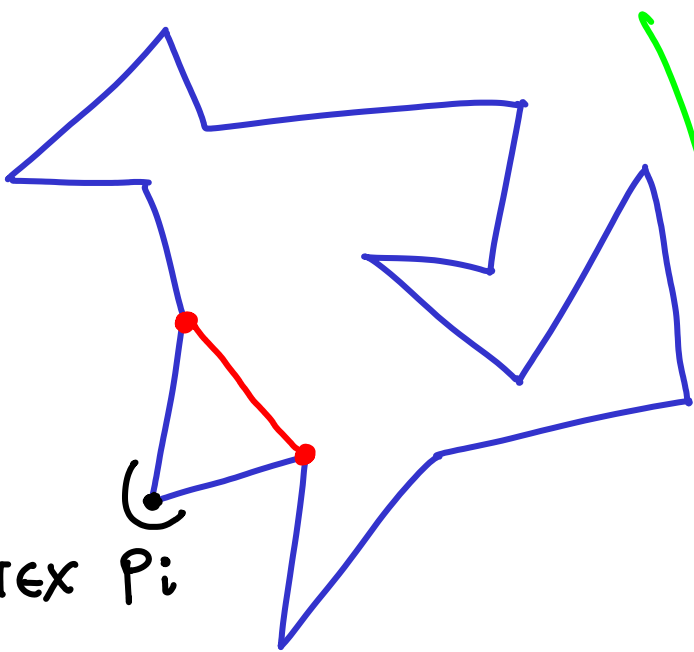
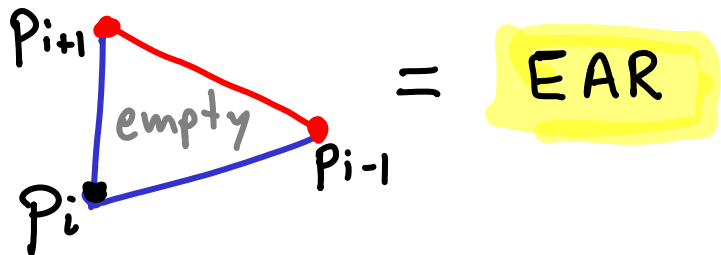
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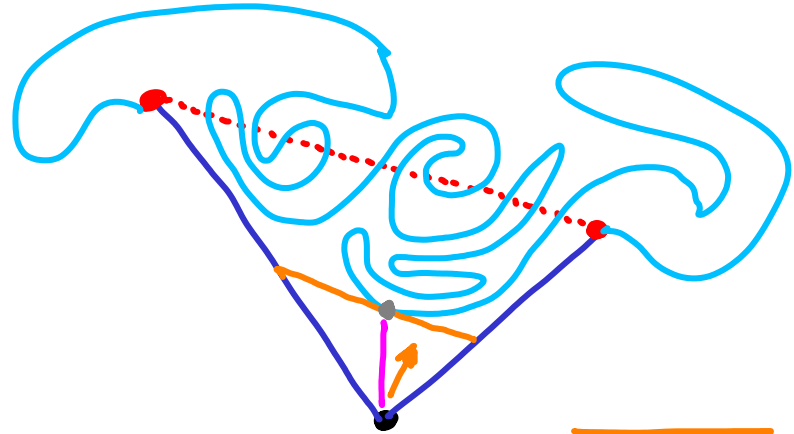
What if the triangle is not empty?



- PICK A CONVEX VERTEX P_i
- TRY $P_{i-1} P_{i+1}$
- IF NOT INTERSECTED, DONE.



What if the triangle is not empty?



SWEEP parallel to $\overline{P_{i-1} P_{i+1}}$
 JOIN to first vertex found. DONE

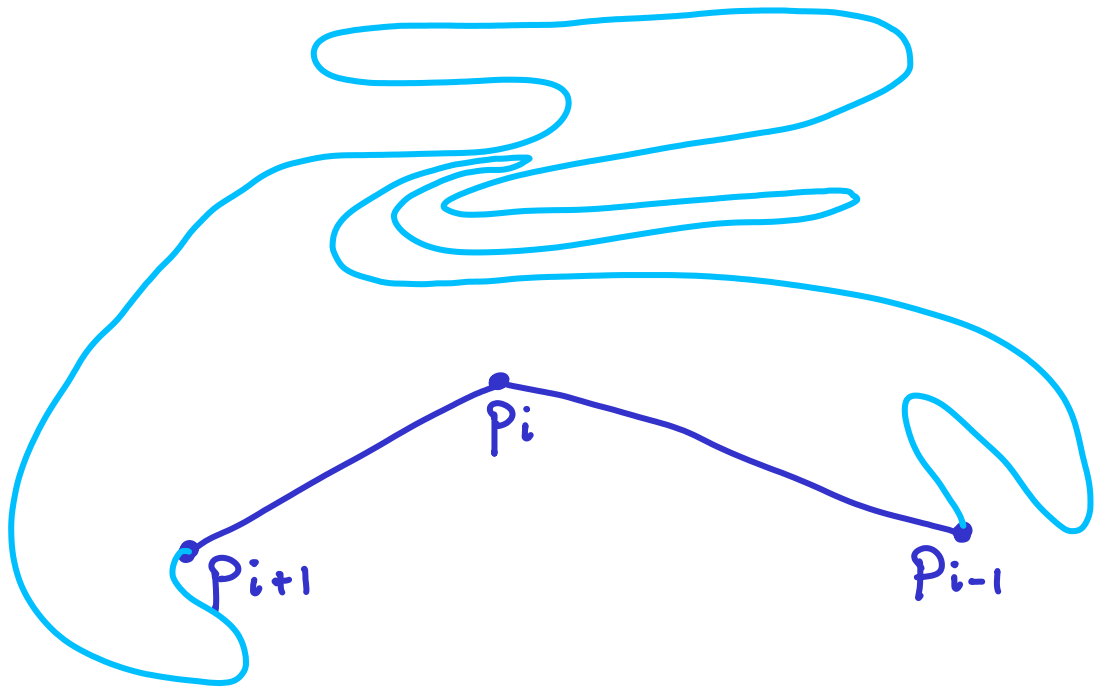
TIME : $O(n)$

(assumes some basic knowledge of comp.geom, for instance that testing if a point is above a line, or testing if two segments intersect, takes constant time.)

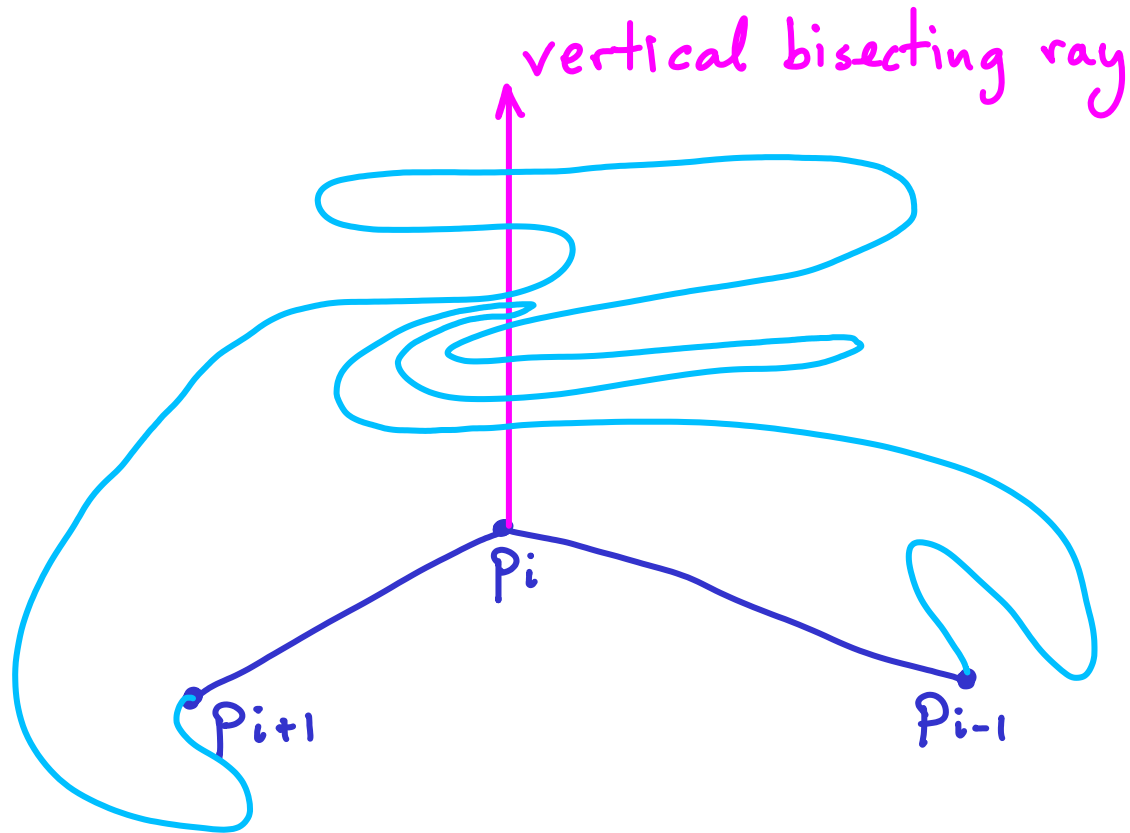
What if I prefer to start with a reflex vertex
(assuming non-convex polygon)

Can we still do it?

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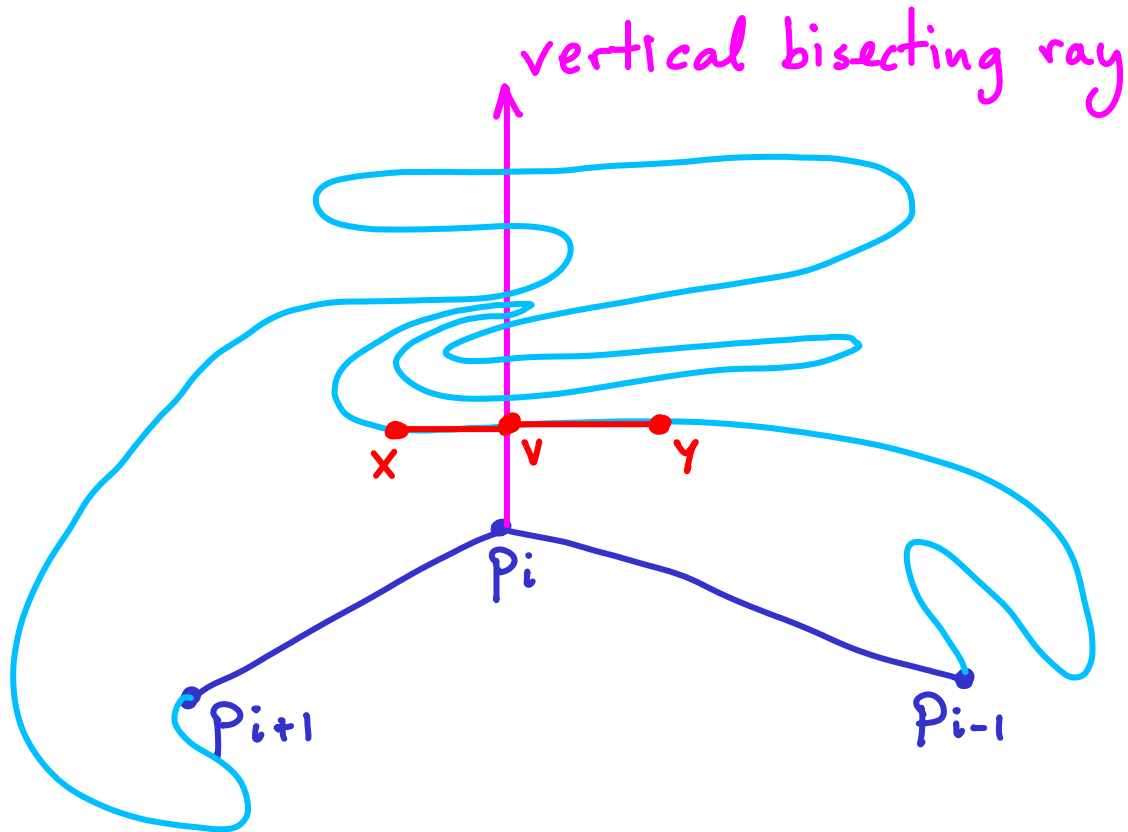


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Assume bisecting ray is vertical
↳ wlog, by rotation

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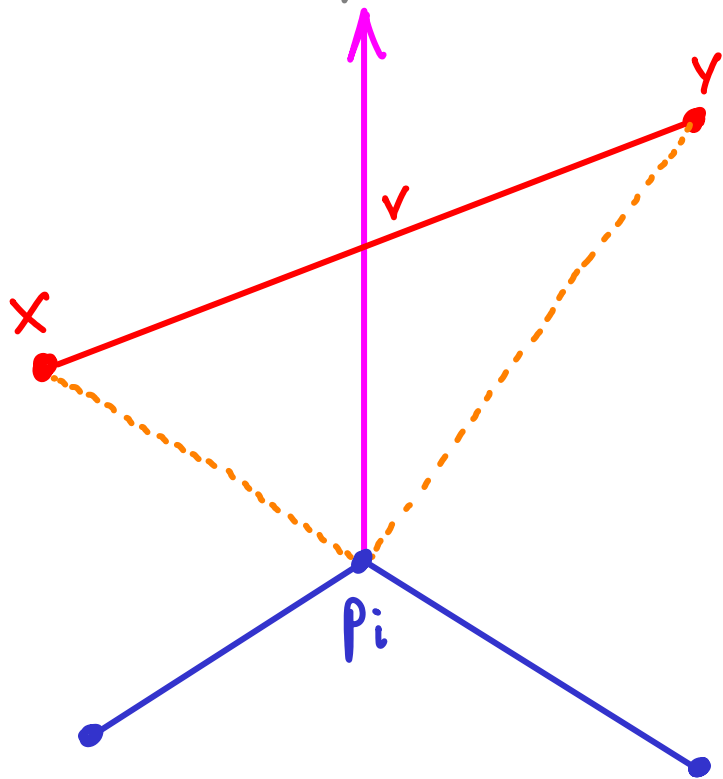


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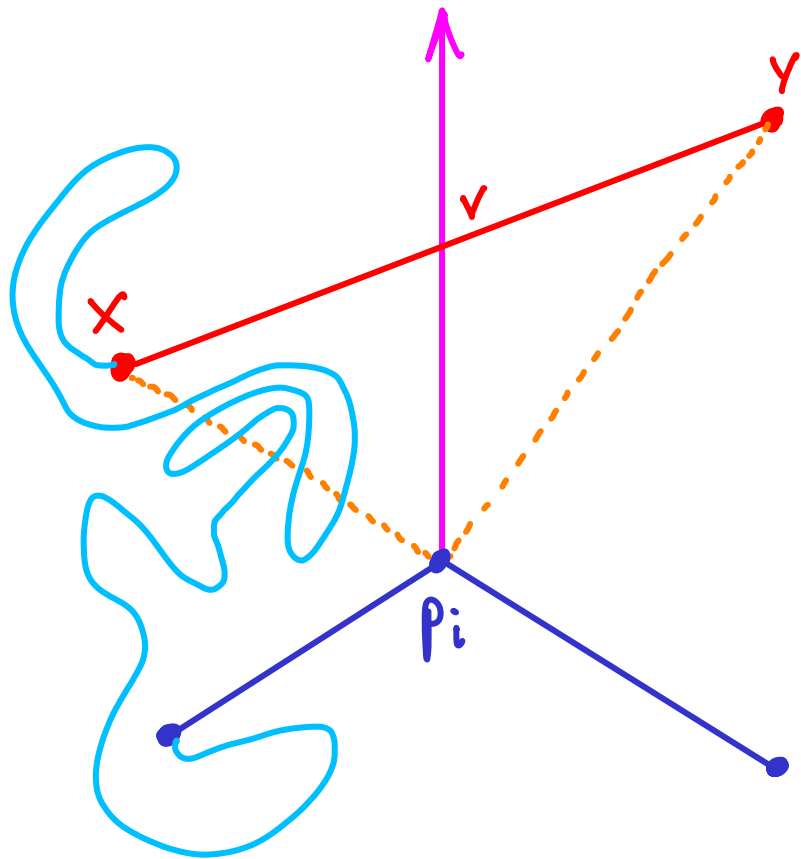
Let v be the first point hit,
on segment \overline{xy}

If v is a vertex: done

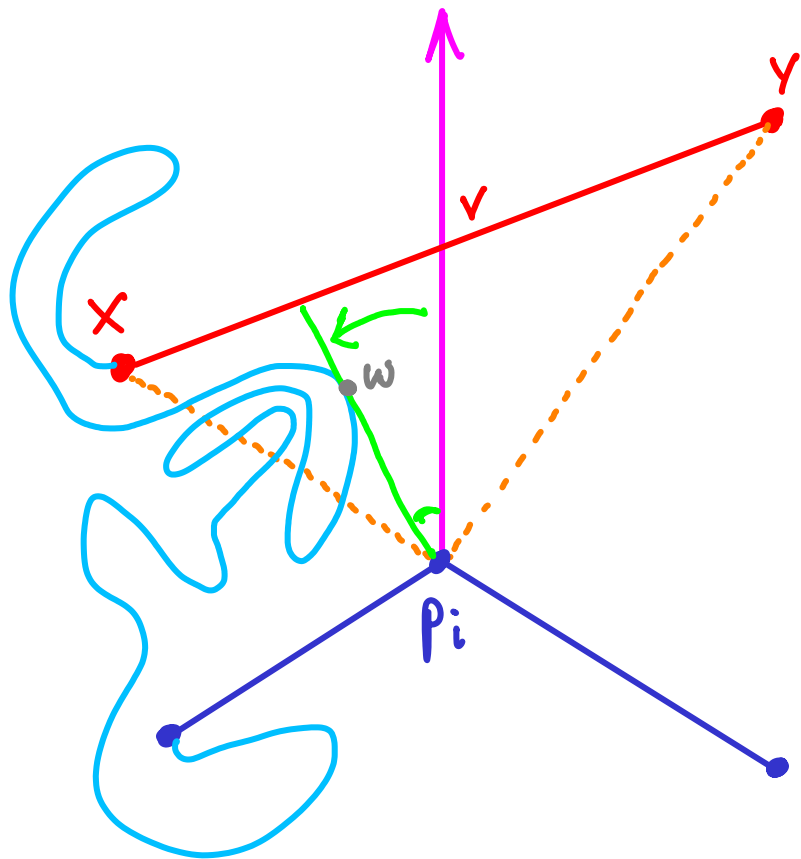
(v is not a vertex)



Try $\overline{p_i x}$.



Try $\overline{p_i x}$. If not a diagonal then polygon must cross it

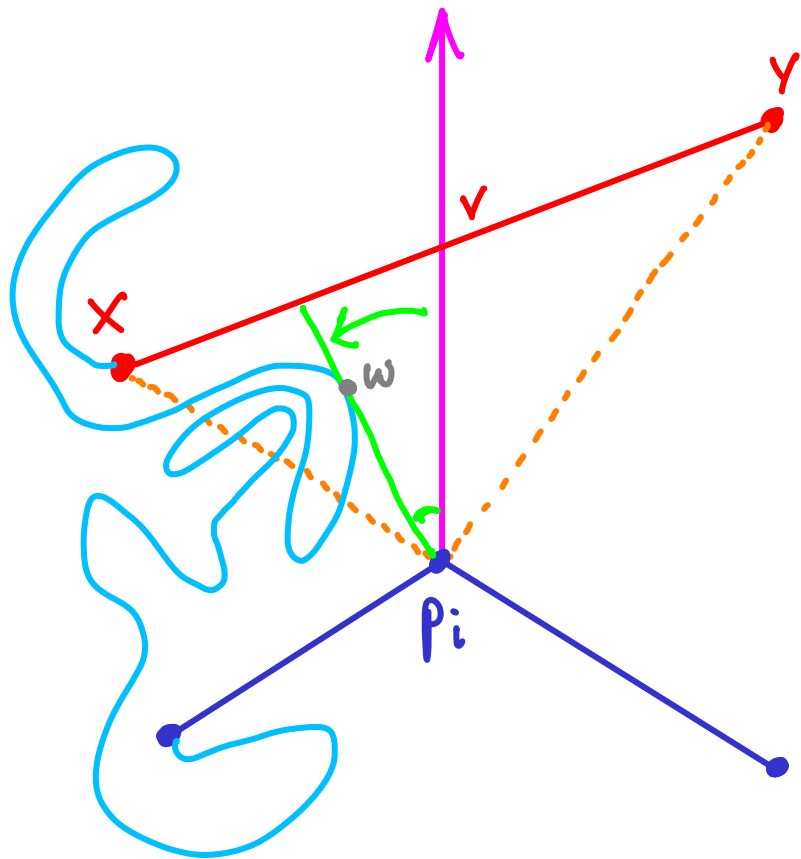


Try $\overline{p_i x}$. If not a diagonal then polygon must cross it

Then **sweep** inside $\Delta x v p_i$
 [rotational fixed at p_i]

Because Δ not empty, will hit w.

QED



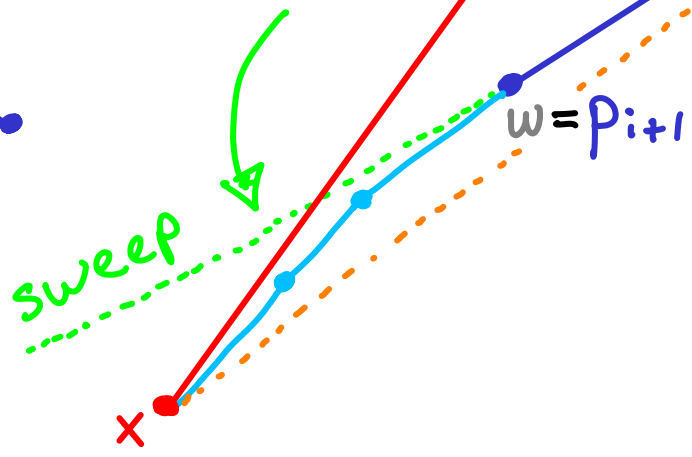
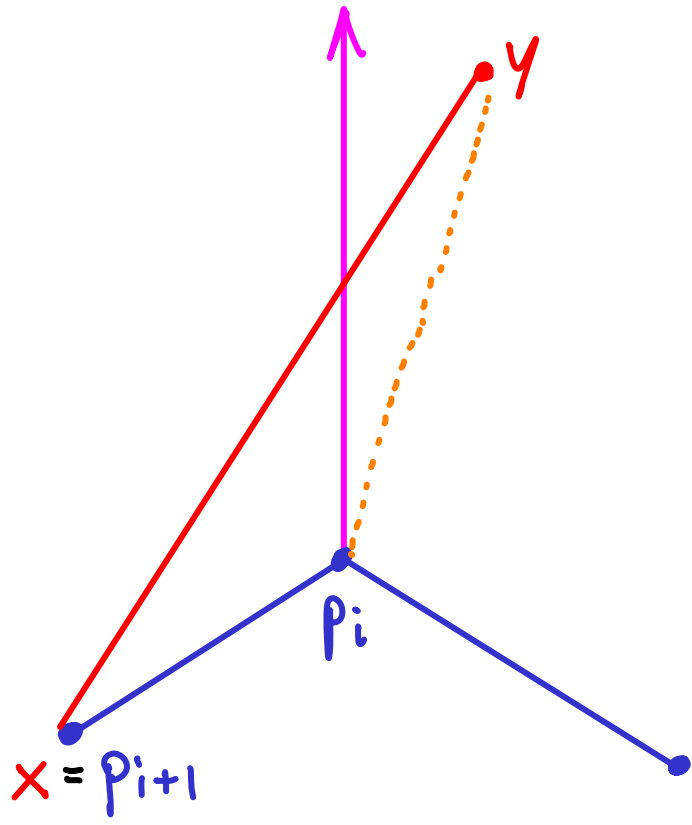
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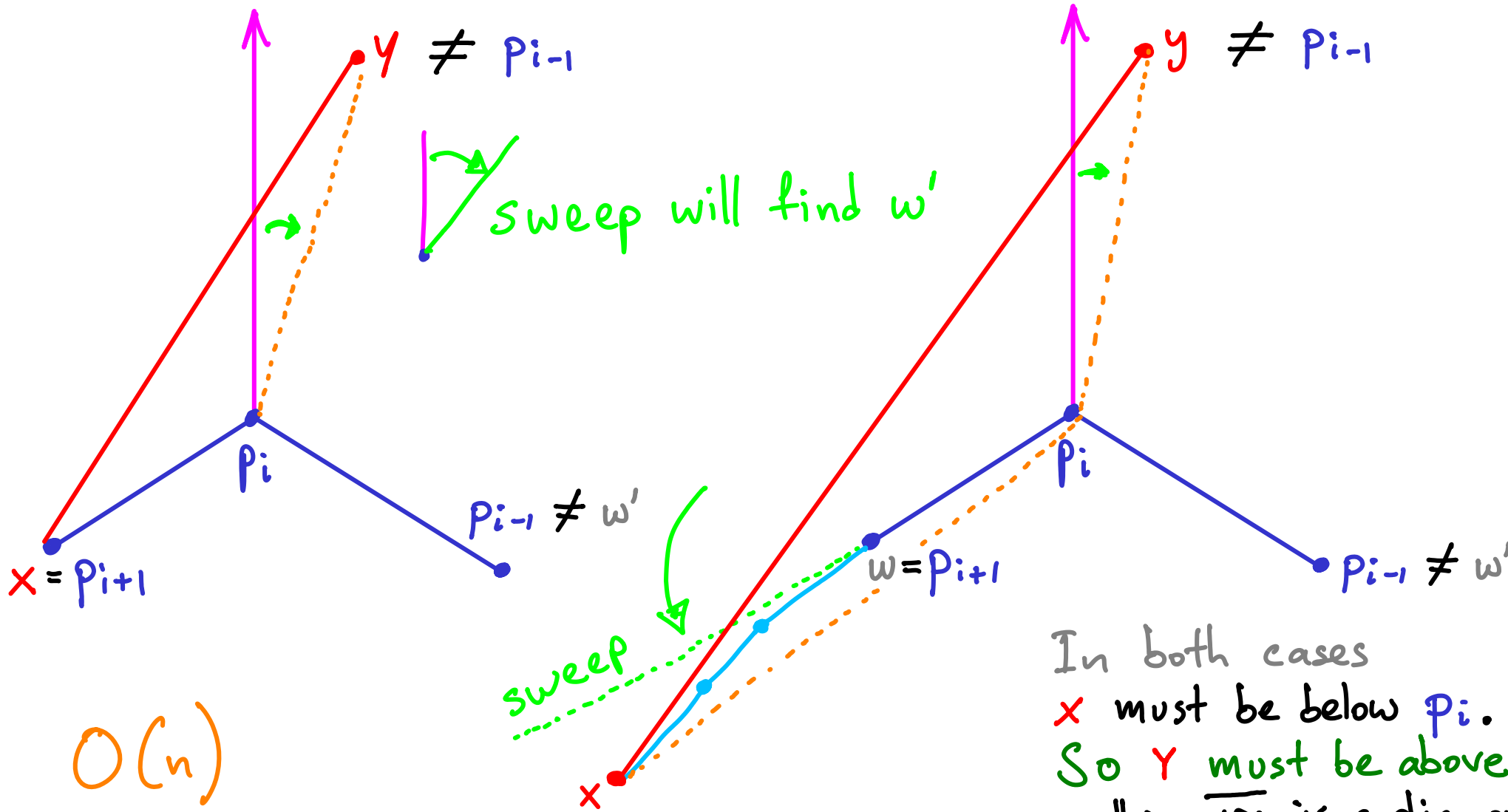
Because Δ not empty, will hit w.

QED ??? **NO**

- What if $\overline{w p_i}$ is a polygon edge?
 $\hookrightarrow w = p_{i+1}$
- What if $x = p_{i+1}$?



In both cases
 x must be below p_i .



TRIANGULATION

- partition of polygon into triangles
- insertion of diagonals while possible

How do we know it exists for every n -gon?

TRIANGULATION

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How do we know it exists for every n -gon?

- We can find one diagonal
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↳ Assume every $(n-1)$ -gon can be triangulated
Base case = \triangle

Algorithm?

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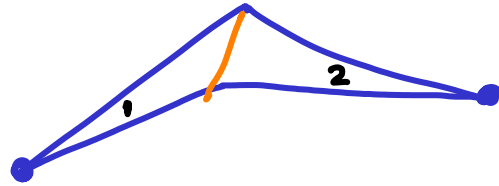
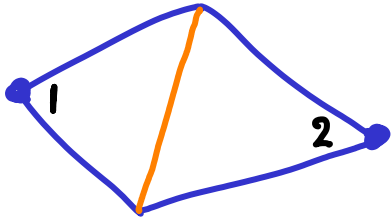
↳ Assume every $(n-1)$ -gon can be triangulated

Base case = \triangle

Algorithm? $\rightarrow O(n)$ for diagonal ... could form EAR & $(n-1)$ -gon
 $O(n^2)$

Meister's two-ear theorem

Every n -gon has ≥ 2 non-overlapping ears. ($n > 3$)



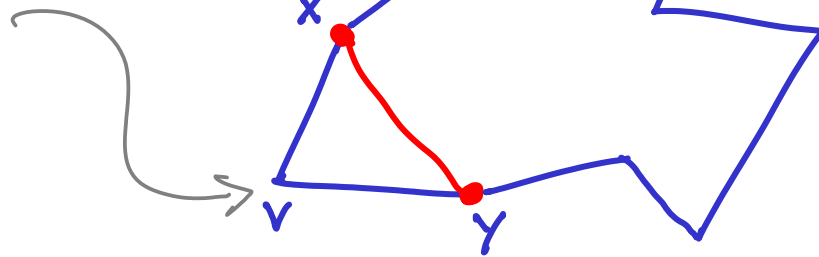
← Base case: $n=4$

Notice: adjacent (convex) vertices can't form a pair.

proof?

proof

- Find a convex vertex.
If it's an ear, cut it off.



proof

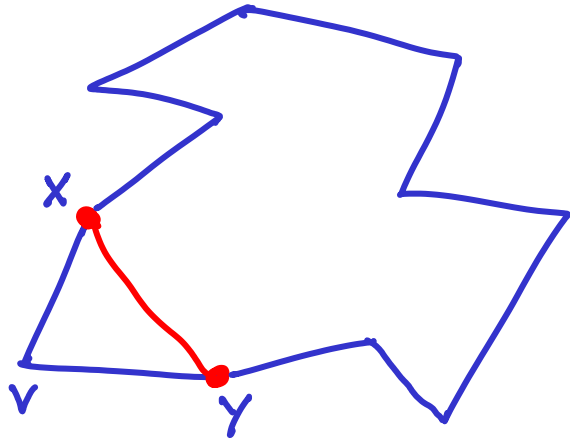
- Find a convex vertex.

- If it's an ear, cut it off.

- Apply induction.

- On sub-polygon, there are ≥ 2 ears.

They can't be at x AND y.
So one ear must not overlap v.



proof

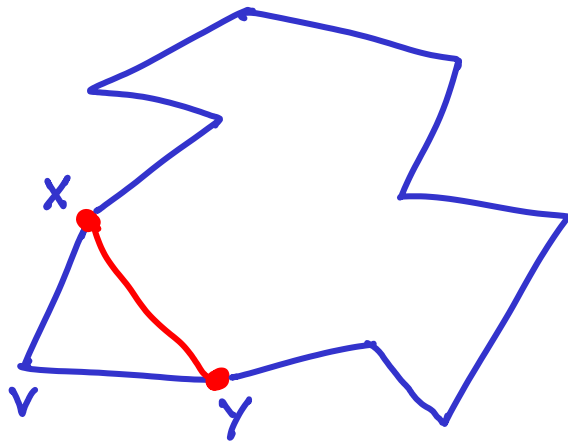
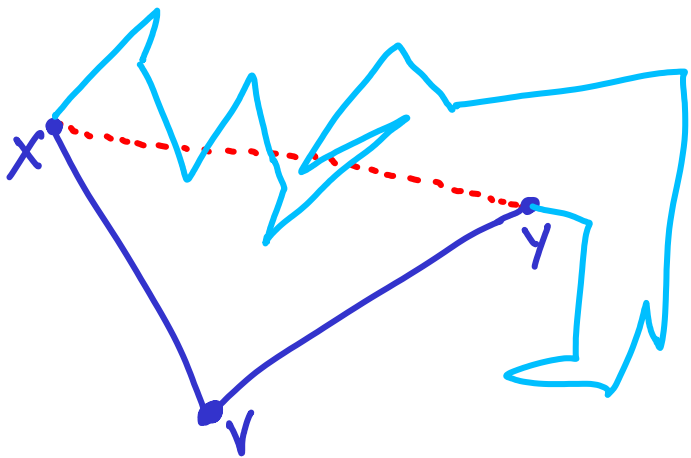
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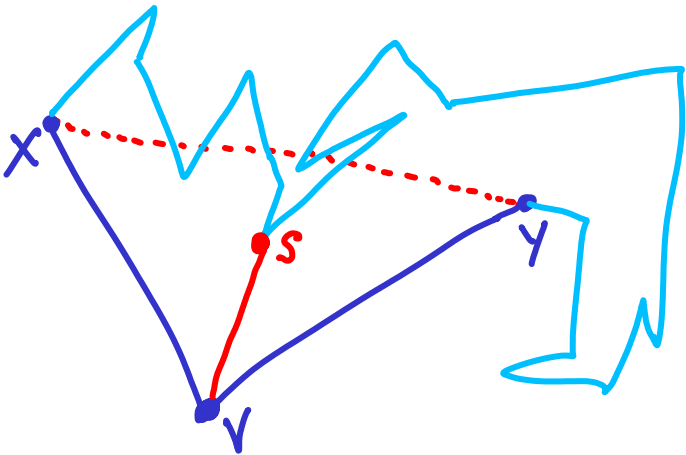
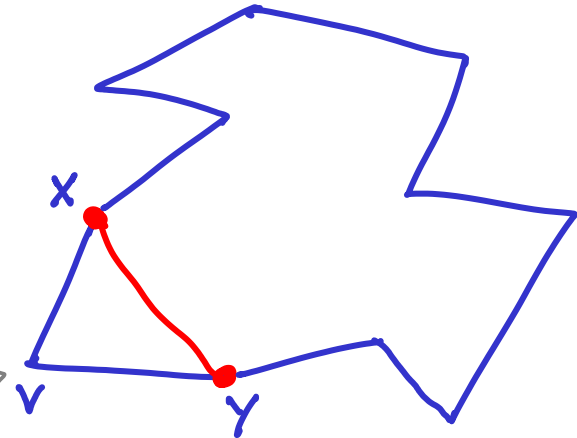
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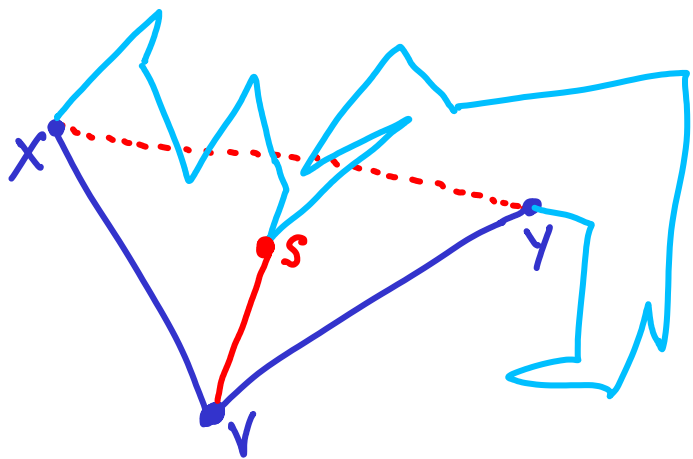
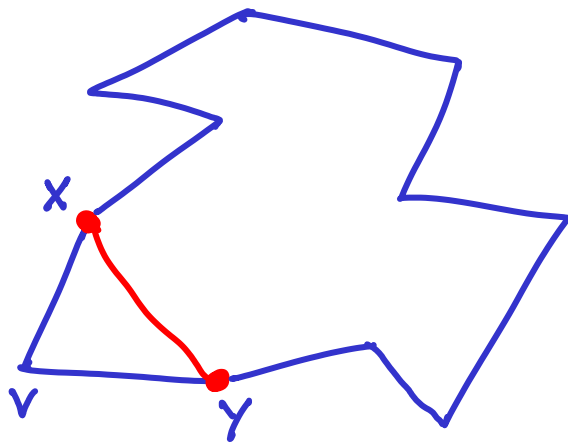
Then find diagonal \overline{vs} as shown before.

↳ By induction, both sub-polygons have 2 ears

As above, not both can be on \overline{vs} .

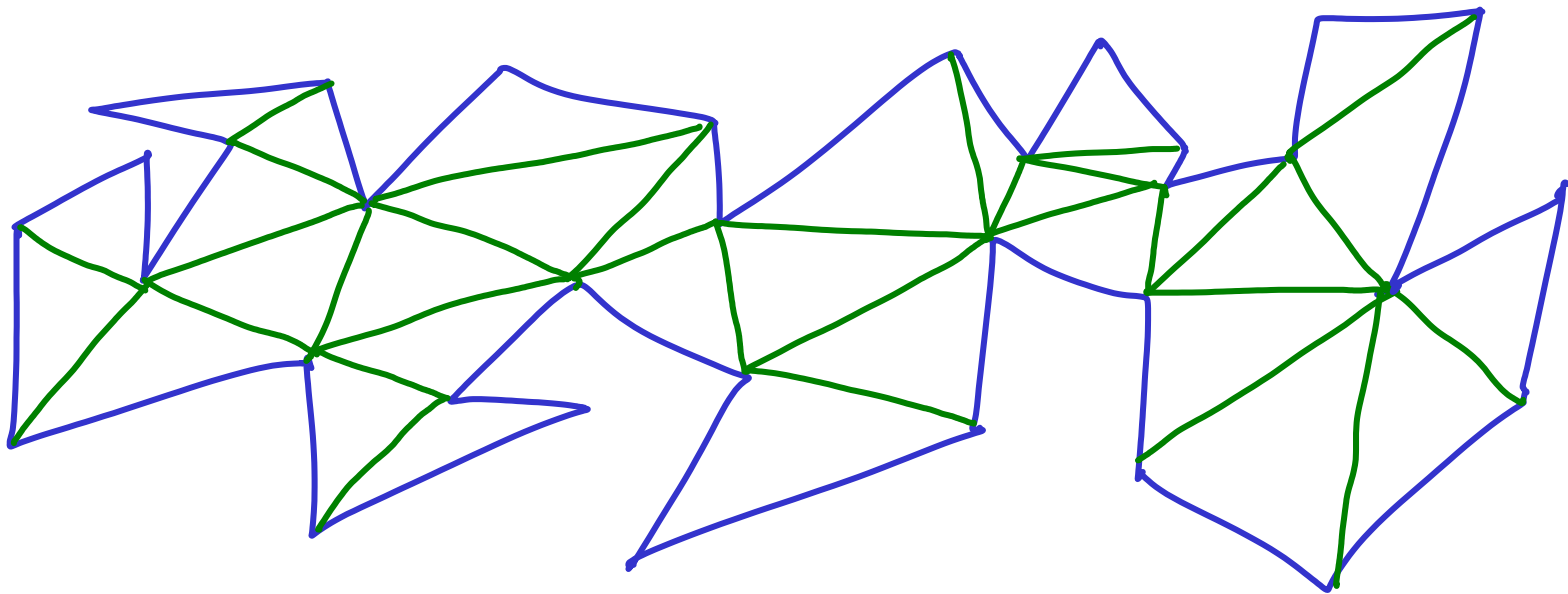
On each side take the ear not at v or s .

QED.



Faster proof of 2-ear than.

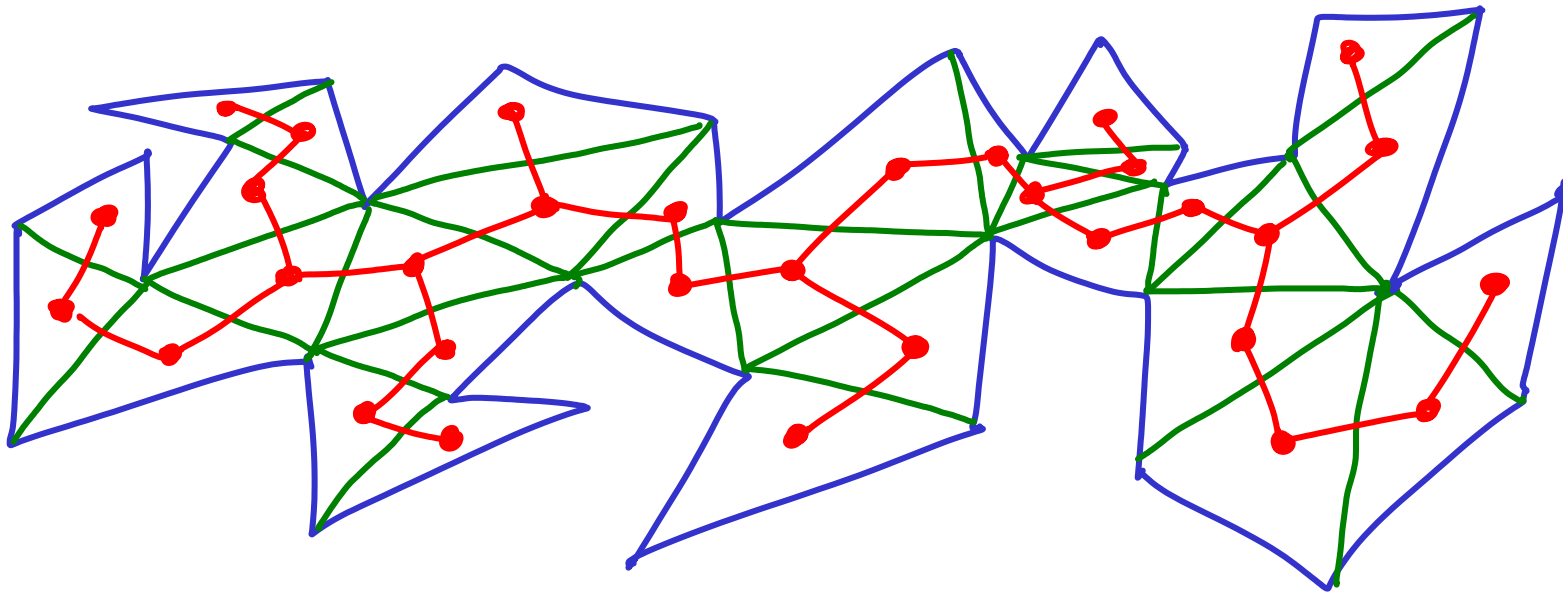
Every polygon has a triangulation.



Faster proof of 2-ear theorem.

Every polygon has a triangulation.

- Every triangulation has a dual tree.

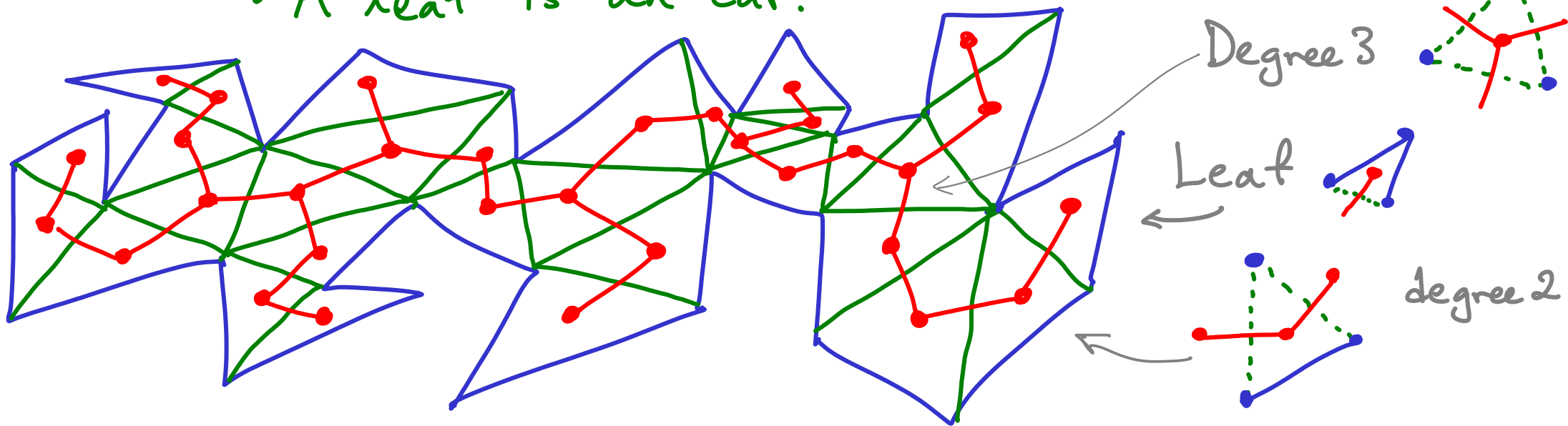


Faster proof of 2-ear thm.

Every polygon has a triangulation.

Every triangulation has a dual tree.

- Every tree has ≥ 2 leaves.
- A leaf is an ear.



The "fast" proof assumes triangulations exist.

↳ requires a proof like what we started with
(existence of diagonal)

The first proof by induction relies on nothing

How long does it take to find one ear?

How LONG DOES IT TAKE TO FIND ONE EAR?

↳ just finding diagonal and searching one side : $O(n^2)$

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↳ A little better:

- List all convex vertices
- Try each one : $O(n)$

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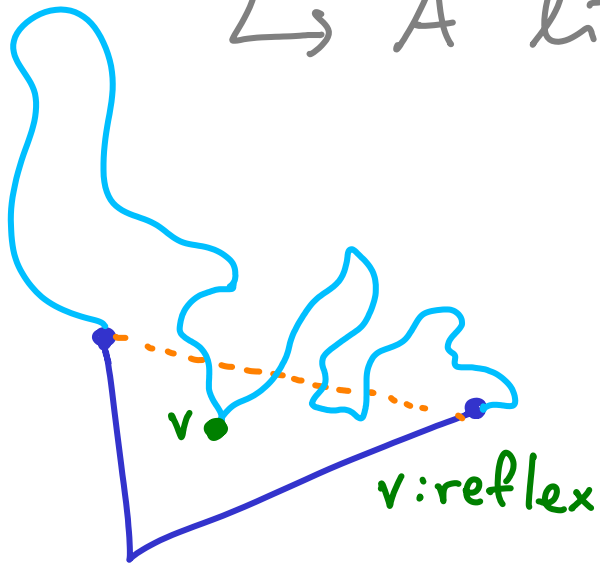
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- still $O(n^2)$ {
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How LONG DOES IT TAKE TO FIND ONE EAR?

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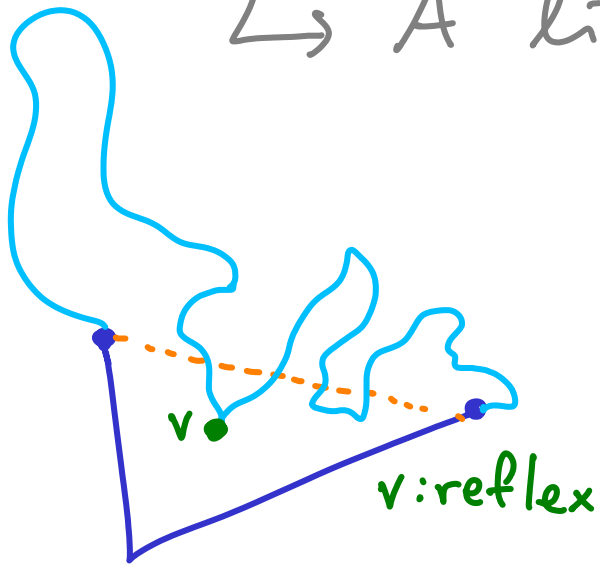
{

- List all convex vertices
- Try each one : $O(n)$
↳ by looking for reflex vertices inside

How LONG DOES IT TAKE TO FIND ONE EAR?

↳ just finding diagonal and searching one side : $O(n^2)$

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still
 $O(n^2)$

{

- List all convex vertices
- Try each one : $O(n)$

↳ by looking for reflex vertices inside $O(k)$

$O(nk)$

if k reflex

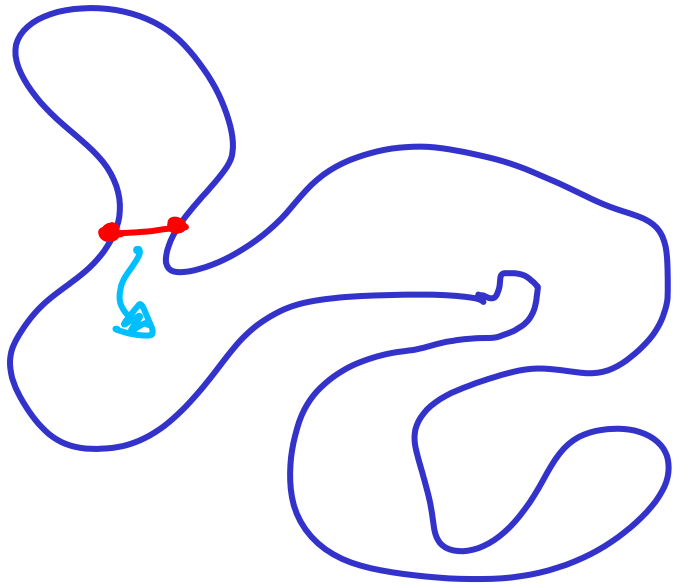
If you have k convex, also $O(nk)$

if $k = \Theta(n)$, still $O(n^2)$

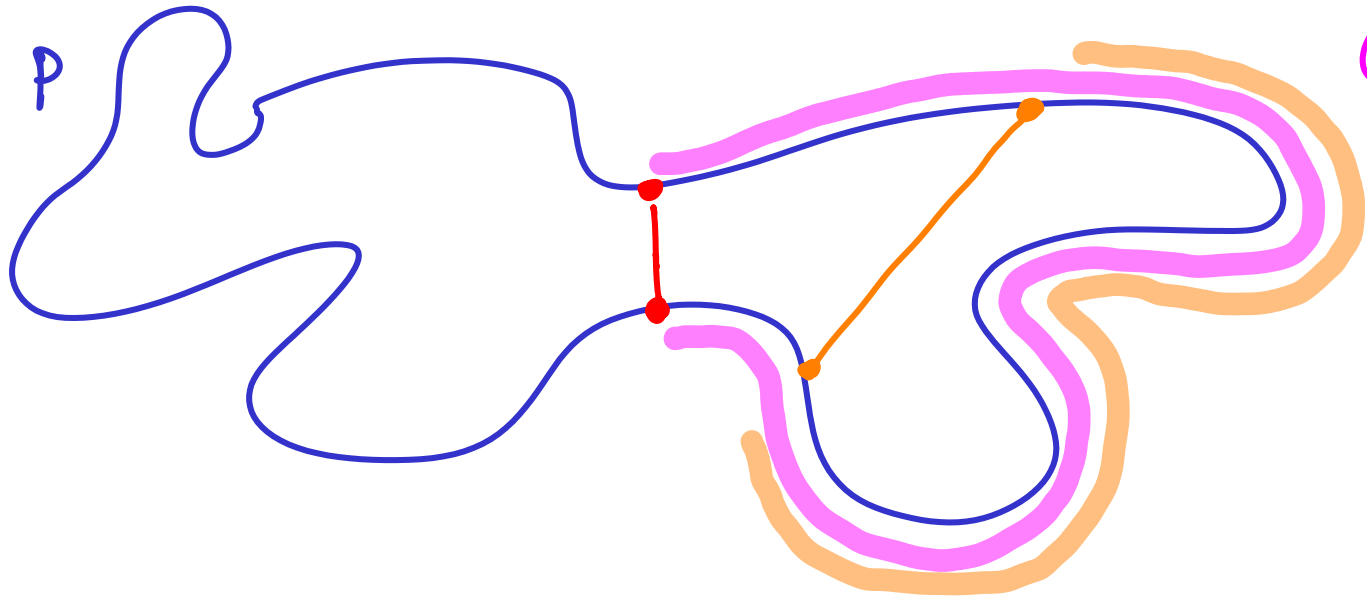
How LONG DOES IT TAKE TO FIND ONE EAR?

↳ just finding diagonal and searching one side : $O(n^2)$

What about searching both sides?



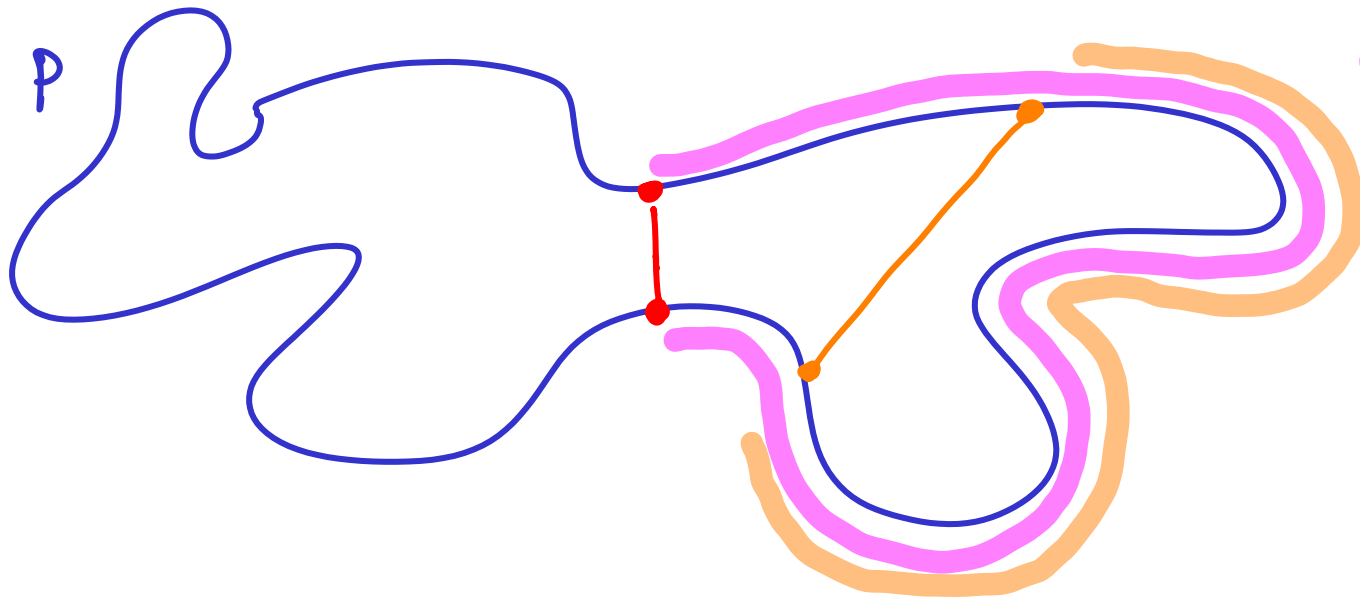
You would have to make unbalanced cuts and go the wrong way each time to get $O(n^2)$



GOOD SUB-POLYGON(P)



- subset
- has only one new edge



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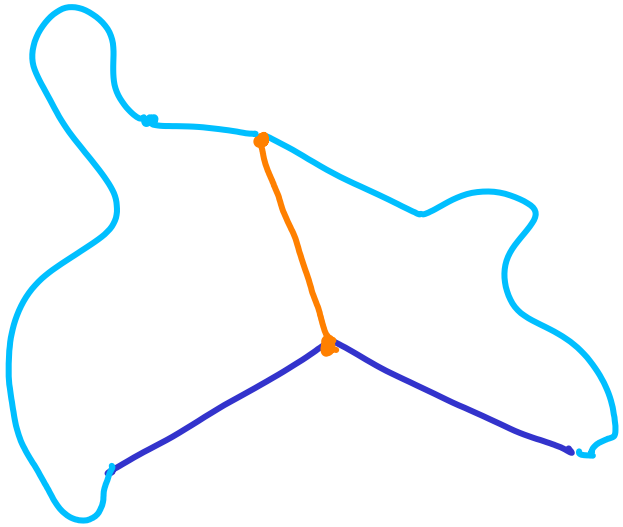
Every time you partition a GSP
with a diagonal,
one of the two sides is still a GSP
(of the original)

FINDING an EAR in LINEAR TIME

- Pick any vertex : test if its an ear $O(n)$ by sweep

FINDING an EAR in LINEAR TIME

- Pick any vertex : test if its an ear $O(n)$ by sweep
- If not \rightarrow form a diagonal $O(n)$
 - \rightarrow choose one side, arbitrarily
 - \rightarrow find ear on that side



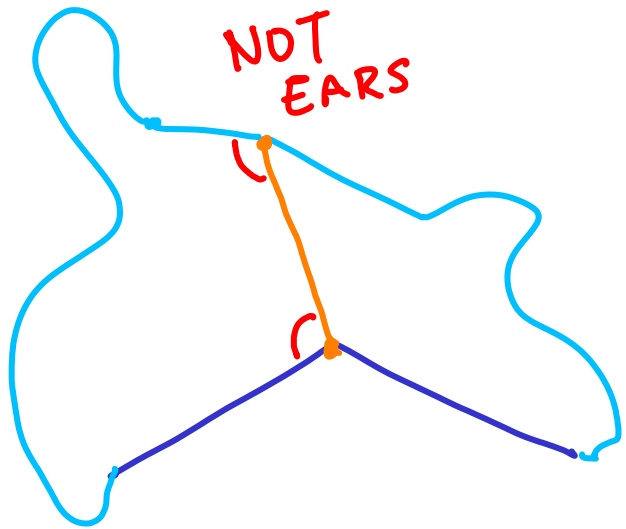
FINDING an EAR in LINEAR TIME

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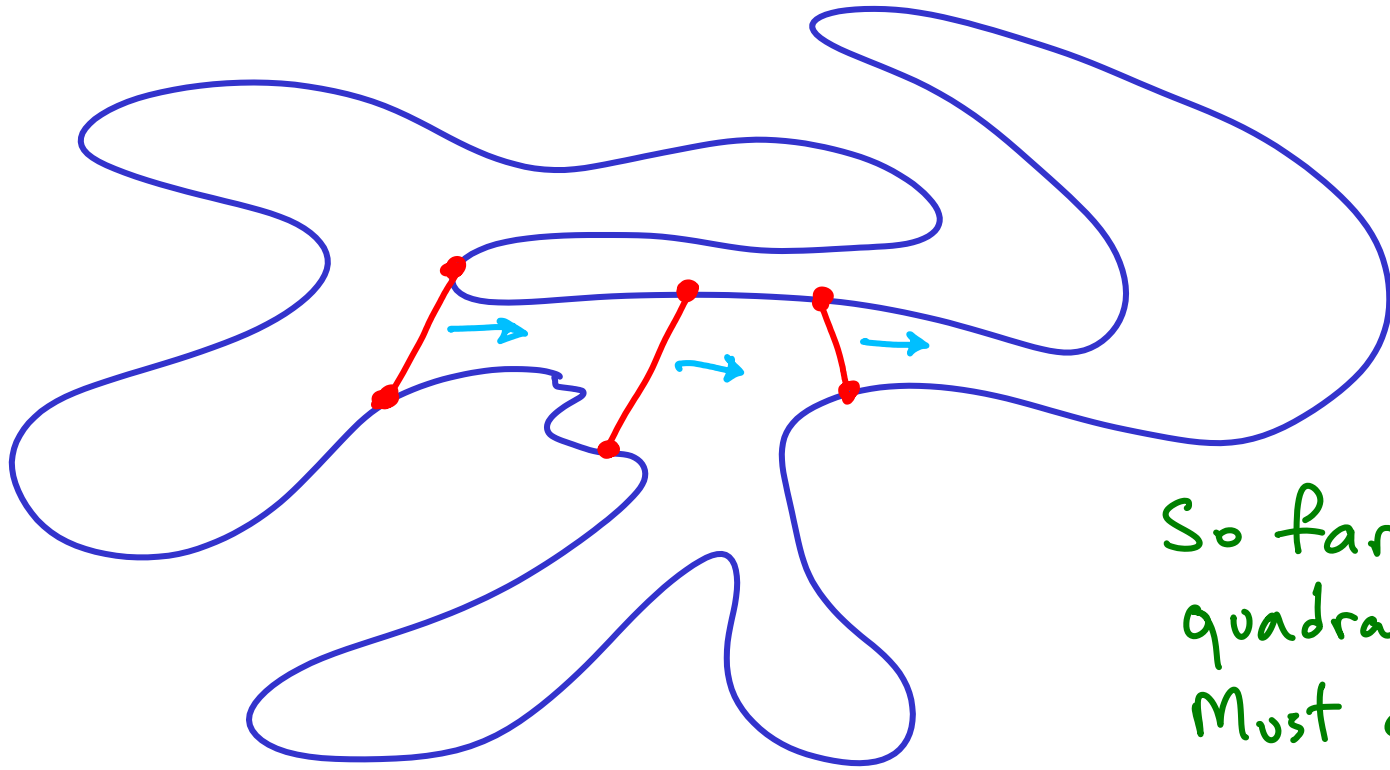
\rightarrow find ear on that side

\hookrightarrow find a particular ear
(can't involve diagonal)



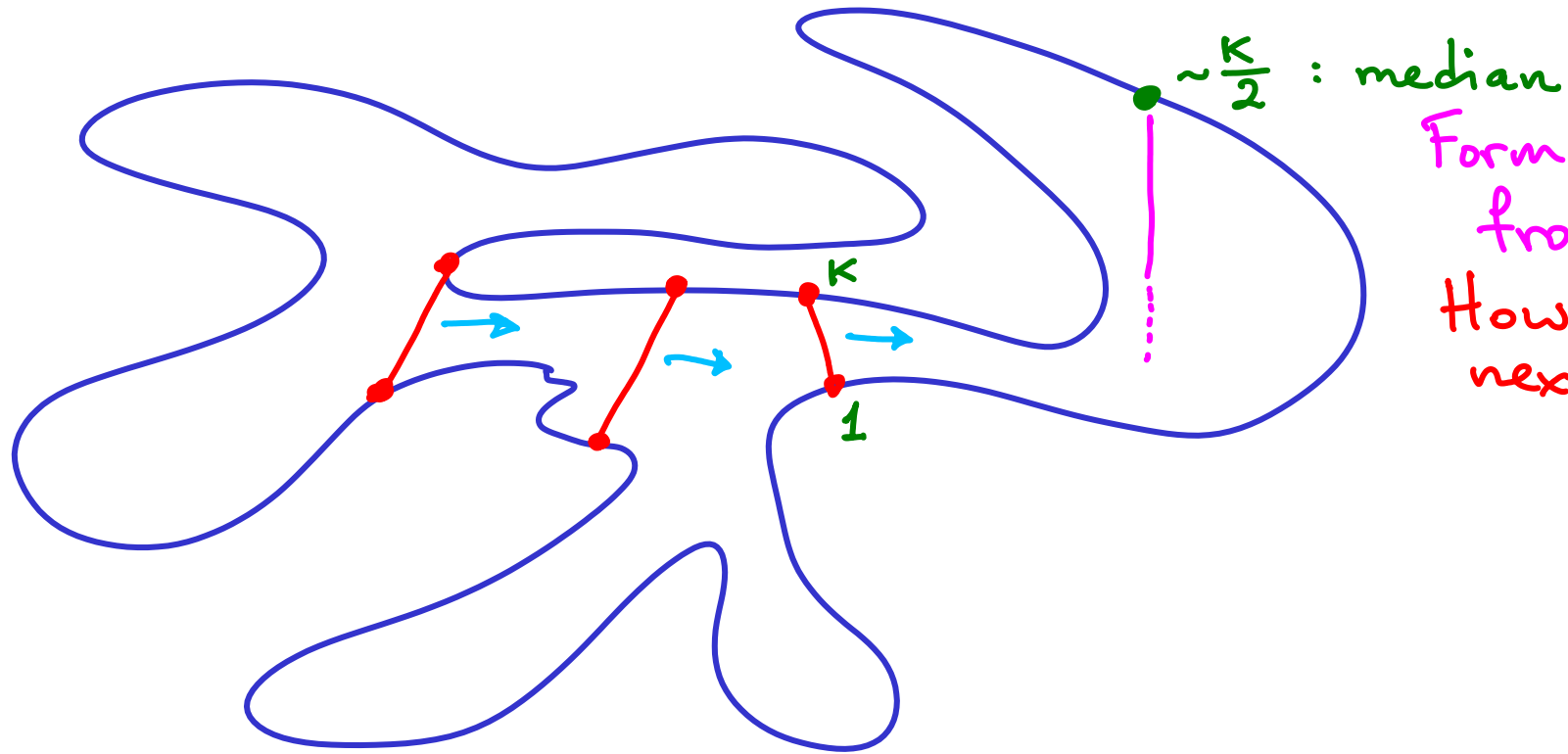
We have seen that when we cut a polygon with a diagonal, one of the 2 ears of each subpolygon is not on the diagonal.

So our first choice of sub-polygon was arbitrary
but we will choose the GSP side each time



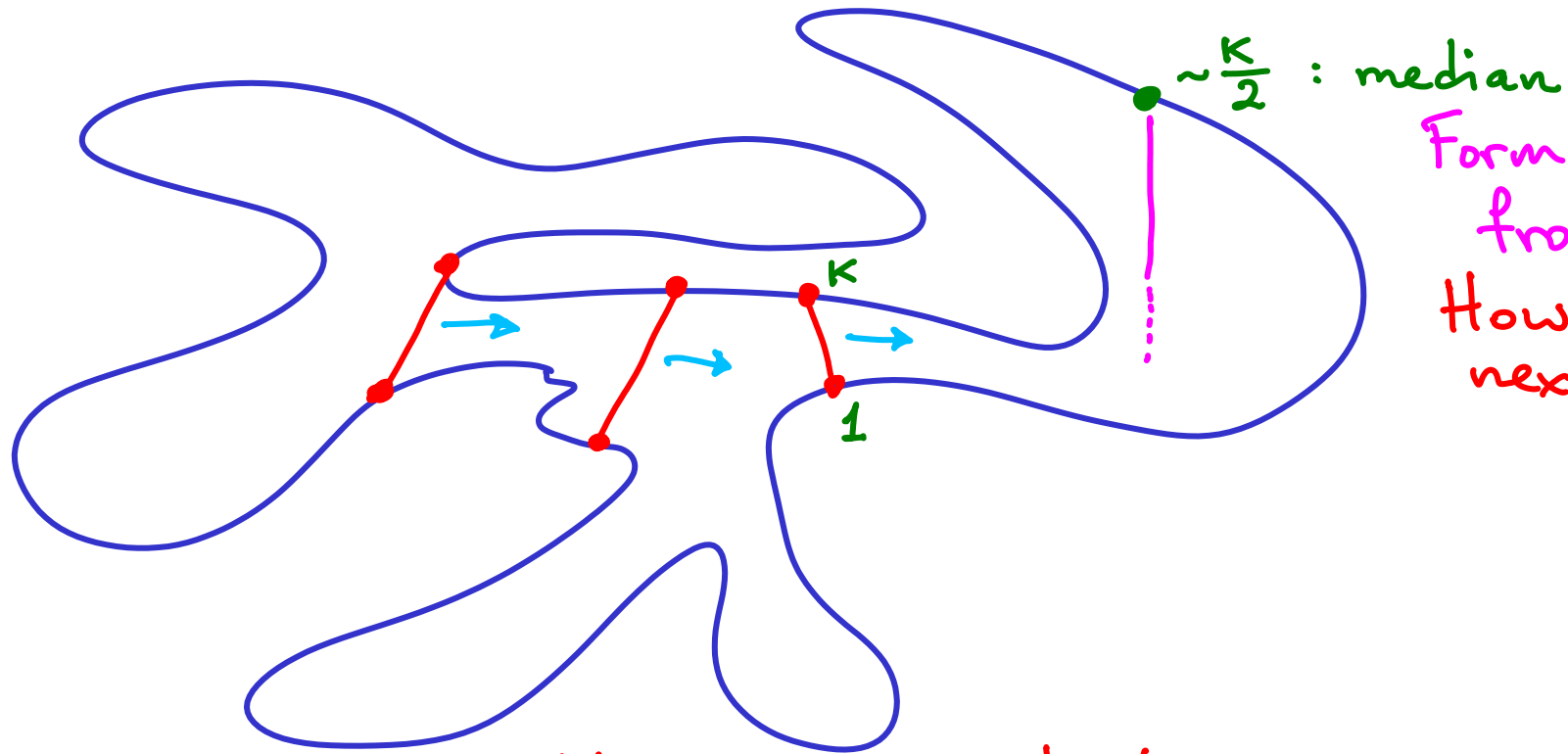
So far this is still
quadratic.
Must choose diagonal carefully

So our first choice of sub-polygon was arbitrary
but we will choose the GSP side each time



Form next diagonal
from here
How big is the
next GSP?

So our first choice of sub-polygon was arbitrary
but we will choose the GSP side each time



Form next diagonal
from here
How big is the
next GSP?

Divide the problem size each time : prune & search